



Attempt all questions. Assume any missed data. Full mark is 50

Q.1) Correct the errors, if any, in each of the following statements:

[5 Marks]

إذا كانت الجملة صحيحة يكتب رقم الجملة وعلامة (✓) فقط أمامها، أما إذا كانت الجملة خطأ فتوضع علامة (x) أمام رقم الجملة. وتعد كتابة الجملة كاملة بعد تصحيحها.

- The complement of a grey-scale image is its photographic negative.
- In point processing, a pixel's grey value is changed without any knowledge of its surrounds.
- In maximum filter, the minimum value of the ordered pixel values is taken.
- Gaussian noise can be cleaned by using frequency domain techniques.
- The shifting property places the dc coefficient in the top right corner of the matrix.
- Adaptive filters are a class of filters which change their characteristics according to the values of the grey-scales under the mask.
- In a ramp edge, the grey values change slowly.
- The human visual system is particularly attuned to two things: edges, and color.
- Saturation is the amount by which the color has been diluted with white.
- Color processing must be done using RGB color model.

Q.2) Give a short answer to each of the following questions:

[15 Marks]

- "Recently, waves of terrorism attacks are beginning to spread from one place to another and thus a proper security approach needs to be adopted by the government". How can image processing helps in this situation?



- "The result of applying a linear filter may be values outside the range (0-255)". Suggest two different methods to overcome this problem.
- "Image restoration concerns the removal or reduction of degradations which have occurred during the acquisition of the image". Give a mathematical model of image degradation. Comment on the resulting model.

- iv. "An appropriate use for the Laplacian is to find the position of edges by locating zero crossings". Define the terms 'Laplacian' and 'Zero crossing'. State the main steps of Marr-Hildreth method.

Q.3.a) Use MATLAB to read the image "liga.jpg". Transform it into grey-scale. Add 5% Gaussian noise to the image. Attempt to remove noise using average filtering (Size 3x3). Obtain the edges of the original color image using RGB color model. [5 Marks]



Q.3.b) Given a 5x5 image, X , and a Roberts edge detector, H

$$X = \begin{bmatrix} 115 & 110 & 105 & 105 & 350 \\ 105 & 100 & 100 & 100 & 355 \\ 100 & 140 & 120 & 100 & 350 \\ 110 & 130 & 145 & 115 & 345 \\ 120 & 130 & 130 & 125 & 345 \end{bmatrix} \quad \& \quad H = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Apply the given edge detector to the image? Modify values outside the range [0-255]. Then, apply a suitable threshold to transform the resulting image into a binary one. [10 Marks]

Q.4.a) Derive the parametric form of a straight line in an image. Use the Hough transform to detect the two strongest lines in the binary image shown below. [10 Marks]

		X						
		0	1	2	3	4	5	6
y	0	1	0	0	0	0	0	1
	1	1	1	0	0	0	0	0
	2	0	0	0	0	0	0	0
	3	1	0	0	1	0	0	0
	4	0	0	0	0	0	0	0
	5	1	0	0	0	0	1	0
	6	0	0	0	0	0	0	1

Q.4.b) Suppose a 4-bit grey-scale image has the following grey values distribution:

i	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
n_i	10	50	100	45	80	40	20	10	0	0	0	0	0	0	0	5

- Sketch the histogram of this image. What do you expect about the appearance of this image?
- Use histogram stretching to improve the appearance of the image. Sketch the result.

Hint: Use the following stretching function: $j = \frac{14-2}{7-1}(i-1)+2, \quad 1 \leq i \leq 7$

- Repeat the solution using histogram equalization. Sketch the result.

[10 Marks]

☺ Best wishes ☺

Assoc. Prof. Hossam El-Din Moustafa

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b. ✓

C-X

d. x

$$e-x$$

f. ✓

g. ✓

h-✓

i - ✓

j-x

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b) Scaling Transformation:

$$y = 255 \frac{x - g_L}{g_H - g_L}$$

9L

iii - In spatial domain, the Convolution results some forms of degradations. $Y(x,y) = X(x,y) * h(x,y)$

We must consider noise n .

$$Y(x,y) = X(x,y) * h(x,y) + n(x,y)$$

Applying the Fourier transformation

$$Y(i,j) = X(i,j) \cdot H(i,j) + N(i,j)$$

If we know the values of H, N then

$$X(i,j) = \frac{Y(i,j) - N(i,j)}{H(i,j)}$$

Comment :- we have problem by dividing on spatial filter because if the spatial filter has small values close to zero then the noise may dominate the output.

V - * Laplacian :-

- May be obtained by considering the second derivatives in both directions (x,y) $\nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2}$

$$\text{mask} \begin{bmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

used as H-P-F

* Zero Crossing :-

To be pixels whose values satisfy either of the following:-

1 - They have negative grey values and are next to a pixel whose value is positive.

2 - They have value of Zero and are between negative and positive.

steps of Marr-Hildreth method:-

1 - Smooth the image with gaussian filter.

2 - Convolve the result with Laplacian.

3 - Find the Zero Crossings in the image

Q.3) a. `m = imread('liga.jpg');`
`y = rgb2gray(m);`
`n = imnoise(y, 'gaussian', 0, 0.05);`
`f = fspecial('average', [3x3]);`
`x = filter2(f, n);`
`imshow(x)`

→ `e1 = edge(m(:,1,1));`
`e2 = edge(m(:,2,2));`
`e3 = edge(m(:,3,3));`
`T = e1 | e2 | e3;`
`figure, imshow(T);`

b) By applying the mask over the image from left to right then step down and to left again and so on.

The result will be:

$$\begin{bmatrix} 15 & 10 & 5 \\ -35 & -20 & 0 \\ -30 & -5 & 5 \end{bmatrix}$$

after modify the values out the range

- clip values $< 0 \rightarrow 0$
 $> 255 \rightarrow 255$

the result =

$$\begin{bmatrix} 15 & 10 & 5 \\ 0 & 0 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

we choose a threshold value $\rightarrow 128$
 $> 128 \rightarrow 1$
 $< 128 \rightarrow 0$

The result in binary:

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Q.4.a) line ① \rightarrow slope = m
 line ② \rightarrow slope = m_1
 $m_1 m = -1$ (line ① \perp line ②)

$$m = \tan \theta = \frac{r \sin \theta}{r \cos \theta} = \frac{\sin \theta}{\cos \theta}$$

$$m_1 = \frac{-1}{m} = \frac{-1}{\tan \theta} = \frac{-\cos \theta}{\sin \theta} \rightarrow \text{①}$$

$$m_1 = \frac{y - y_1}{x - x_1} = \frac{y - r \sin \theta}{x - r \cos \theta}$$

from ①, ② $\therefore \frac{-\cos \theta}{\sin \theta} = \frac{y - r \sin \theta}{x - r \cos \theta}$

$$-x \cos \theta + r \cos^2 \theta = y \sin \theta - r \sin^2 \theta$$

$$r \cos^2 \theta + r \sin^2 \theta = y \sin \theta - x \cos \theta$$

$$r (\cos^2 \theta + \sin^2 \theta) = y \sin \theta - x \cos \theta$$

$$r = y \sin \theta - x \cos \theta \quad (-90^\circ \leq \theta \leq 90^\circ)$$

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Q.4.a)

(x, y)	-90°	-45°	0	45°	90°
(0, 0)	0	0	0	0	0
(0, 1)	-1	-0.7	0	0.7	1
(0, 3)	-3	-2.1	0	2.1	3
(0, 5)	-5	-3.5	0	3.5	5
(1, 1)	-1	-1.4	-1	0	1
(3, 3)	-3	-4.2	-3	0	3
(5, 5)	-5	-7.1	-5	0	5
(6, 0)	0	-4.2	-6	-4.2	0
(6, 0)	-6	-8.5	-6	0	6

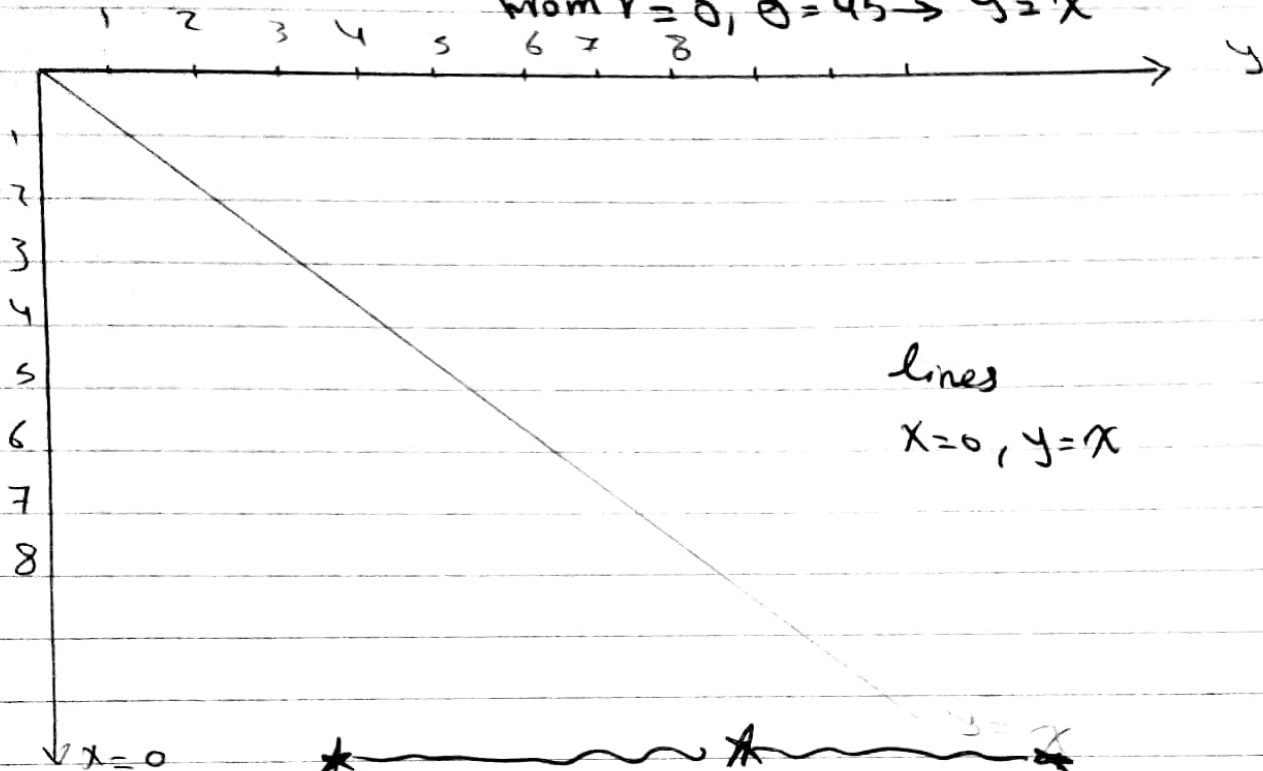
$$r=0, \theta=0$$

$$r=0, \theta=45$$

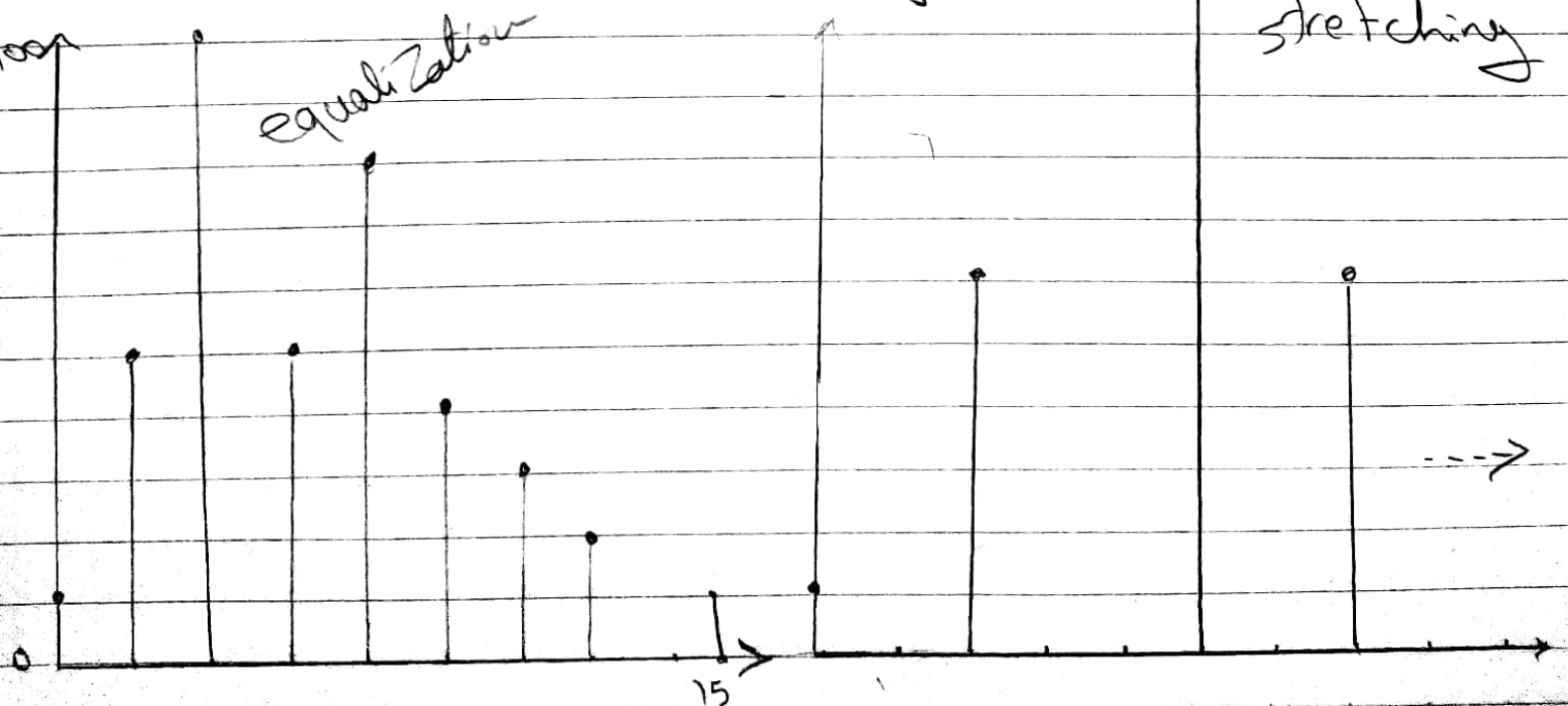
$$r = y \sin \theta - x \cos \theta$$

$$\text{From } r=0, \theta=0 \rightarrow 0 = x$$

$$\text{From } r=0, \theta=45^\circ \rightarrow y = x$$



i- it will be Bad Contrast image (dark image) because values are clustered at low end of histogram.



iii. $L = 16$, $\frac{L-1}{n} \sum n_i = \frac{1}{24} \sum n_i$, $n = \sum n_i = 360$

i	n_i	$\sum n_i$	$\frac{1}{24} \sum n_i / (\frac{L-1}{n} \sum n_i)$	j
0	10	10	0.4	0
1	50	60	2.5	3
2	100	160	6.66	7
3	45	205	8.54	9
4	80	285	11.875	12
5	40	325	13.54	14
6	20	345	14.375	14
7	10	355	14.7	15
8	0	355	14.7	15
9	0	355	14.7	15
10	0	355	14.7	15
11	0	355	14.7	15
12	0	355	14.7	15
13	0	355	14.7	15
14	0	355	14.7	15
15	5	360	15	15

